

# subtraction of vectors in physics

## Introduction to the Subtraction of Vectors in Physics

**subtraction of vectors in physics** is a fundamental operation that, much like vector addition, underpins our understanding of numerous physical phenomena. From calculating the resultant displacement after a series of movements to analyzing forces acting on an object, mastering vector subtraction is crucial for any aspiring physicist or engineer. This article will delve deep into the concept, breaking down its graphical and analytical methods, exploring its applications, and providing clear, actionable insights. We'll cover everything from the basic definition to more complex scenarios, ensuring you gain a comprehensive grasp of how to subtract vectors effectively. Prepare to demystify this essential physics concept and unlock its practical utility.

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## Understanding Vector Subtraction

At its core, subtracting one vector from another is conceptually similar to adding the negative of that vector. Imagine you have two vectors, A and B. When we talk about  $A - B$ , we are essentially performing the operation  $A + (-B)$ . This simple rephrasing is key to understanding the mechanics of vector subtraction and how it relates to the familiar concept of vector addition. Vectors possess both

magnitude and direction, and the subtraction must account for both these properties to yield a correct result. It's not as straightforward as subtracting scalar quantities; the directional aspect introduces complexities that require specific mathematical tools.

The resultant vector, often denoted as  $R$ , represents the difference between the initial vectors. For instance, if vector  $A$  represents an object's initial position and vector  $B$  represents its final position, then  $A - B$  might represent a change in position or displacement, depending on the context.

Conversely,  $B - A$  would represent the displacement from the initial to the final position. The order of subtraction is critical;  $A - B$  is generally not the same as  $B - A$ . This is a crucial point to remember when working with vector quantities, as reversing the order will result in a vector of the same magnitude but opposite direction.

## Graphical Methods for Vector Subtraction

Visualizing vector subtraction can be incredibly helpful in building intuition. The primary graphical method leverages the concept of adding the negative vector. To subtract vector  $B$  from vector  $A$  graphically ( $A - B$ ), you first represent vector  $A$ . Then, you reverse the direction of vector  $B$  to obtain  $-B$ . Finally, you connect the tail of  $-B$  to the head of  $A$ , and the resultant vector  $R$  is drawn from the tail of  $A$  to the head of  $-B$ . This is often referred to as the "head-to-tail" method, adapted for subtraction.

Another graphical approach, particularly useful when both vectors originate from the same point, is the parallelogram method. If you want to find  $A - B$ , you draw both vectors  $A$  and  $B$  starting from the same origin. Then, you construct a parallelogram where  $A$  and  $B$  are adjacent sides. The vector representing  $A - B$  is then the diagonal of the parallelogram that starts at the origin and points towards the head of  $A$ , if  $B$  were to be subtracted from it. Think of it this way: if  $A$  is your starting point and you move along  $B$ , then  $A - B$  is the vector that brings you back from that final position to where you would have been if you had only moved along  $A$ .

Let's break down the parallelogram method in more detail for clarity.

- Draw both vectors, A and B, originating from the same point.
- Complete the parallelogram by drawing lines parallel to A and B, such that they form a closed four-sided figure.
- The vector  $A - B$  is the diagonal of this parallelogram that starts at the common origin and points towards the head of the vector B when B is subtracted from A. More precisely, it is the diagonal that originates from the point where B's head would be if it were subtracted from A's head.

This visual approach helps to solidify the understanding that vector subtraction is about finding the difference in displacement or effect between two vector quantities.

## Analytical Method for Vector Subtraction

While graphical methods offer intuition, the analytical method provides precise numerical answers, especially in two or three dimensions. This method relies on expressing vectors in terms of their components along the Cartesian coordinate axes (x, y, and sometimes z). If vector A has components  $(A_x, A_y)$  and vector B has components  $(B_x, B_y)$ , then the vector subtraction  $A - B$  is simply the subtraction of corresponding components. Therefore, the resultant vector  $R = A - B$  will have components  $(R_x, R_y)$  where  $R_x = A_x - B_x$  and  $R_y = A_y - B_y$ .

For vectors in three-dimensional space, the process is analogous. If  $A = (A_x, A_y, A_z)$  and  $B = (B_x, B_y, B_z)$ , then  $A - B = (A_x - B_x, A_y - B_y, A_z - B_z)$ . This component-wise subtraction is incredibly powerful because it reduces a complex geometric operation into a series of simple arithmetic subtractions. Once you have the components of the resultant vector, you can easily calculate its magnitude using the Pythagorean theorem ( $\sqrt{R_x^2 + R_y^2}$  for 2D, and  $\sqrt{R_x^2 + R_y^2 + R_z^2}$  for 3D) and its direction using trigonometric functions (like  $\arctan(R_y/R_x)$ ).

Consider a practical example using the analytical method:

1. Define your vectors in component form. For example, let  $A = (3, 4)$  and  $B = (1, 2)$ .
2. Perform component-wise subtraction:  $A - B = (3 - 1, 4 - 2) = (2, 2)$ .
3. The resultant vector  $R$  is  $(2, 2)$ .
4. To find the magnitude of  $R$ :  $\text{magnitude}(R) = \sqrt{2^2 + 2^2} = \sqrt{4 + 4} = \sqrt{8} = 2\sqrt{2}$ .
5. To find the direction of  $R$ :  $\text{angle} = \arctan(2/2) = \arctan(1) = 45$  degrees with respect to the positive x-axis.

This step-by-step breakdown illustrates the systematic nature of the analytical approach.

## Applications of Vector Subtraction in Physics

The subtraction of vectors is not merely an academic exercise; it has profound and practical applications across various branches of physics. One of the most straightforward applications is in calculating displacement. If a person walks 5 meters east (vector  $A$ ) and then 3 meters west (vector  $B$ ), their net displacement from the starting point is not simply  $5 - 3$ . Instead, if we define east as the positive direction, then  $A = (5, 0)$  and  $B = (-3, 0)$ . The total displacement is  $A + B = (5 + (-3), 0 + 0) = (2, 0)$ , meaning they are 2 meters east of their starting point. However, if we want to find the change in displacement from position  $A$  to position  $B$ , we'd calculate  $B - A$ . Let's consider a different scenario: if your initial position is represented by vector  $P1$  and your final position by vector  $P2$ , your displacement is  $P2 - P1$ . This difference vector encapsulates the net change in your location.

Another critical area where vector subtraction is employed is in analyzing forces. When multiple forces act on an object, the net force (or resultant force) determines the object's acceleration. If you have an

applied force ( $F_{\text{applied}}$ ) and a friction force ( $F_{\text{friction}}$ ) acting in opposite directions, and you want to find the net force that causes motion, you would subtract the friction force from the applied force (assuming they are along the same line but opposing).  $F_{\text{net}} = F_{\text{applied}} - F_{\text{friction}}$ . This calculation is essential for understanding motion, equilibrium, and the dynamics of systems. Furthermore, in electromagnetism, the electric field or magnetic field at a point due to multiple sources can be found by vectorially subtracting the fields generated by individual sources, especially when considering potentials or differences.

Here are some specific examples of its application:

- **Relative Velocity:** To find the velocity of object A relative to object B ( $v_{AB}$ ), you subtract the velocity of B from the velocity of A:  $v_{AB} = v_A - v_B$ . This is crucial in scenarios like aircraft navigation relative to the wind or when two vehicles are moving.
- **Change in Momentum:** The impulse applied to an object is equal to the change in its momentum. If an object's initial momentum is  $p_{\text{initial}}$  and its final momentum is  $p_{\text{final}}$ , the change in momentum is  $\Delta p = p_{\text{final}} - p_{\text{initial}}$ . This involves vector subtraction as momentum is a vector quantity.
- **Electric Potential Difference:** While potential is scalar, the electric field, which is related to the rate of change of potential, is a vector. Differences in electric fields or forces can be analyzed using vector subtraction.

These examples highlight the ubiquitous nature of vector subtraction in describing physical interactions.

## Common Pitfalls in Vector Subtraction

Despite its fundamental nature, students often stumble when performing vector subtraction. One of the

most common errors is neglecting the directional aspect. Treating vector subtraction as simple scalar subtraction (e.g., thinking that subtracting a vector of magnitude 5 from a vector of magnitude 7 always results in a magnitude of 2) is a fundamental misunderstanding. Remember, direction is paramount; a vector of magnitude 5 pointing north and a vector of magnitude 7 pointing south will result in a vector of magnitude 12 pointing south when performing the subtraction that yields the net effect.

Another frequent mistake is in the graphical method, specifically in correctly identifying and drawing the resultant vector. Confusion often arises about which vector's tail connects to which vector's head, or which diagonal represents the difference. The key is to consistently apply the rule: to find  $A - B$ , add  $A$  to  $(-B)$ . This means if you draw  $A$ , then draw  $-B$  from the head of  $A$ , the resultant is from the tail of  $A$  to the head of  $-B$ . Similarly, in the parallelogram method, ensure you are drawing the correct diagonal that represents the difference and not the sum.

Furthermore, errors in component-wise subtraction are common, especially with negative signs. If  $B$  has a negative x-component, subtracting  $B$  means adding its absolute value to the x-component of  $A$ . For example, if  $A = (5, 2)$  and  $B = (-3, 1)$ , then  $A - B = (5 - (-3), 2 - 1) = (5 + 3, 1) = (8, 1)$ . A careless mistake with the double negative can lead to an incorrect answer. Always double-check your signs when performing analytical subtractions, especially when dealing with vectors pointing in the negative x, y, or z directions.

## Advanced Concepts in Vector Subtraction

As you progress in physics, you'll encounter more complex scenarios involving vector subtraction. For instance, in rotational dynamics, angular velocities and accelerations, while often represented by vectors, can have intricate relationships when subtracting them, especially when considering different axes of rotation. The concept of torque, which is a cross product of position and force vectors, also involves vector operations where subtraction might be used in analyzing the net torque or changes in angular momentum.

In the realm of special relativity, even velocity addition and subtraction take on a different form, deviating from simple Euclidean vector subtraction. The relativistic velocity addition formula ensures that no object can exceed the speed of light, a departure from classical mechanics. While the underlying principle of finding a resultant vector from two others remains, the mathematical framework for combining them (including subtraction) is modified to adhere to relativistic principles. Understanding these advanced applications requires a solid foundation in the basic principles of vector subtraction and addition, as they are the building blocks for more sophisticated theories.

The principle of superposition also plays a role in advanced vector subtraction. When considering fields, such as electric or magnetic fields, the principle states that the net field at a point due to multiple sources is the vector sum of the fields due to each individual source. If we're interested in the difference between the fields at two points, or the field generated by removing a source, vector subtraction becomes indispensable. This allows us to analyze complex field configurations by breaking them down into simpler, manageable parts and then recombining them using vector operations, including subtraction, to understand the net effect.

## FAQ

### **Q: What is the fundamental difference between vector subtraction and scalar subtraction?**

A: The fundamental difference lies in the inclusion of direction. Scalar subtraction involves only magnitudes, like subtracting 5 from 10 to get 5. Vector subtraction, however, considers both magnitude and direction. Subtracting vector B from vector A ( $A - B$ ) is equivalent to adding vector A to the negative of vector B ( $A + (-B)$ ), meaning the direction of B is reversed before the addition occurs, leading to a resultant vector that has both a magnitude and a direction representing the difference.

### **Q: Can graphical methods be used for vector subtraction in 3D space?**

A: Yes, graphical methods can be extended to 3D space, though they become more challenging to

visualize accurately. The head-to-tail method can be used by drawing vectors in three dimensions. The parallelogram method is also applicable, forming a parallelepiped instead of a parallelogram, with the resultant difference vector being one of its diagonals. However, for precise calculations in 3D, the analytical component method is generally preferred due to its accuracy and ease of execution.

### **Q: Is the order of subtraction important for vectors?**

A: Absolutely, the order of subtraction is critical for vectors. Unlike scalar subtraction where the order might be reversed for absolute difference, for vectors,  $A - B$  is not the same as  $B - A$ . Specifically,  $A - B$  is equal to  $-(B - A)$ . This means that if you reverse the order of subtraction, you get a resultant vector with the same magnitude but pointing in the exact opposite direction.

### **Q: How do you find the magnitude of a resultant vector after subtraction?**

A: Once you have the components of the resultant vector  $R = (R_x, R_y)$  in 2D, you find its magnitude using the Pythagorean theorem:  $|R| = \sqrt{R_x^2 + R_y^2}$ . For 3D vectors  $R = (R_x, R_y, R_z)$ , the magnitude is  $|R| = \sqrt{R_x^2 + R_y^2 + R_z^2}$ . This calculation gives you the length of the resultant vector, representing its magnitude.

### **Q: When is the analytical method for vector subtraction preferred over the graphical method?**

A: The analytical method is generally preferred when precise numerical answers are required, especially in two or three dimensions, or when dealing with complex calculations that are difficult to represent accurately on paper. While graphical methods are excellent for conceptual understanding and visualization, they can be prone to inaccuracies due to drawing imperfections. The analytical method, using components, provides exact values and is less susceptible to subjective interpretation.

## Q: What is the physical interpretation of subtracting two displacement vectors?

A: Subtracting two displacement vectors, say  $D_2 - D_1$ , represents the displacement required to move from the position described by  $D_1$  to the position described by  $D_2$ . If  $D_1$  is your initial position vector and  $D_2$  is your final position vector, then  $D_2 - D_1$  is the net change in position, or the displacement vector from your starting point to your ending point.

## Q: Can vector subtraction be used to find the relative velocity between two objects?

A: Yes, indeed. The velocity of object A relative to object B, denoted as  $v_{AB}$ , is found by subtracting the velocity of object B from the velocity of object A:  $v_{AB} = v_A - v_B$ . This is a fundamental application in kinematics and is crucial for understanding how objects move with respect to each other in various reference frames.

## Q: What happens if you subtract a vector from itself?

A: If you subtract a vector from itself, the result is the zero vector (a vector with zero magnitude and undefined direction, often represented as 0 or (0,0) in 2D). For example,  $A - A = (A_x - A_x, A_y - A_y) = (0, 0)$ . This makes sense conceptually, as there is no difference between something and itself.

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